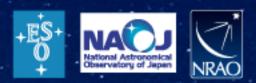


## ALMA Common Software Basic Track

A walk through ACS functionality

I. Oya, CTAO gGmbH



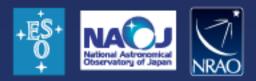


# ♦ ACS services♦ ACS generic GUIs and clients





♦ Every application needs a set of core integration infrastructure services, like for instance:  $\diamond$  messaging (request/response and publish/subscribe) ♦ logging ♦ error management  $\diamond$  alarms  $\diamond$  configuration data ♦ In ACS these services have been identified as essential for the application domain  $\diamond$  These have been implemented mostly on top of standard CORBA Services ♦ DDS/zeroMQ/other implementations or studies to replace at some point CORBA for some of them The ACS work consists in wrapping the implementation to
 simplify their usage by the application developers





 $\diamond$  Enables the communication between system components ♦ Supports both request-response and publish-subscribe message patterns  $\diamond$  anonymous publish/subscribe data transfer is seen more and more as a key need for the messaging system

 $\diamond$  In ACS: ♦ CORBA messaging provides request-response ♦ CORBA Notify Service provides publish-subscribe  $\diamond$  New technologies may replace the Notify Service, offering some advantages  $\diamond$  DDS implementation exists, zeroMQ/other studies

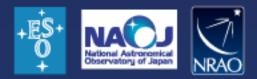




### ACS Command Center: starting/stopping ACS

🕌 (project) - Acs Command Center 📃 🗆 🗙								
Acs Command Center	er							
<u>Project</u> <u>Tools</u> <u>Expert</u>	<u>H</u> elp							
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Containers Name Type Remote Host								

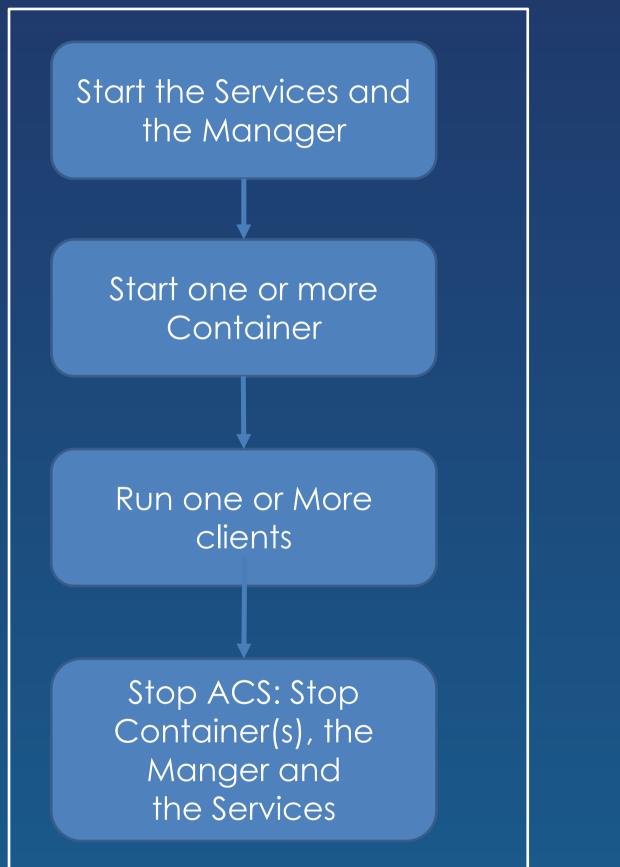


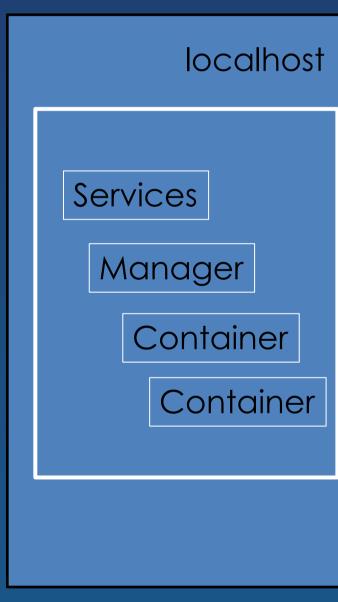




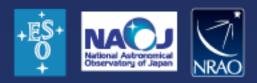
### \*A typical ACS Session

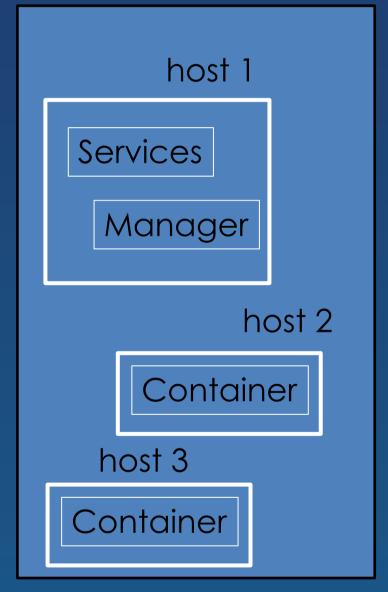
Typical ACS session





Simple deployment scenario





Complex deployment scenario

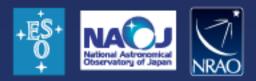


cherenkov telescope array

### \*Simple deployment scenario

≗	(project) - Acs Command Center		
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	Common Settings Acs Instance 0 2 Cdb Root Dir /alma/ACS-2014.2/acsdata/config/defau 3 Start Stop 7	b. с.	Spe Pla <sup>v</sup>
1	<ul> <li>Localhost (single-machine project)</li> <li>Remote (distributed project)</li> <li>Use built-in ssh <ul> <li>Use native ssh</li> <li>Use Acs Daemons</li> <li>Host</li> <li>User Pwd</li> </ul> </li> </ul>	d. e. f.	Spe Spe Stai
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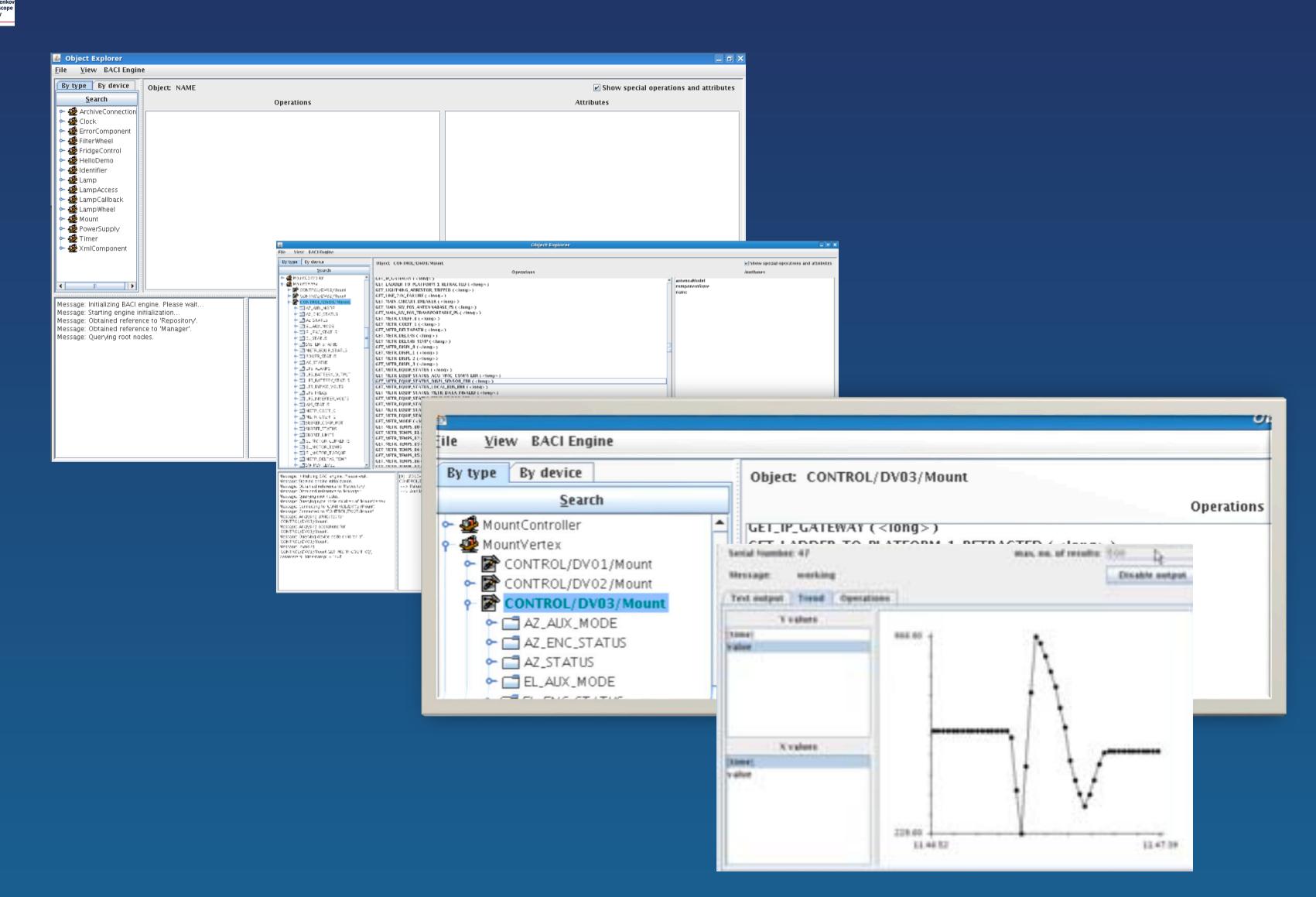
Based on the description Marcus Schilling, that also includes details for the complex case: Link

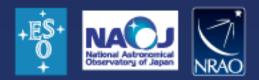


ect localhost (1) ecify ACS instance (2) y button starts Services and manager (3) a. Output logs will show in Log Area (L) b. freshly started Manager now appears in the deployment info view (D) ecify Container Name (4) ecify Container Type (5) rt Container (6) a. More containers can be added via (C)your clients. a. Predetermined clients can be started from (T) p Containers, Manager and Services (7) a. All output goes to the logging area (L) ou encounter problems, and find the Acs sion in an inoperable state, you can empt to terminate it (X)



### Generic client: object explorer



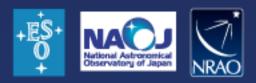




### Generic client: event browser

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🗁 Archive			i i	~								
★ Setautivostyservice	Service	#cons	#suppliers									
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Supplers: 0	Logging	0	1		2009-09-16T14:36:27.570	m1Pos	2328	pttDataEvent				
QueueSize: 0	Notification	10	5		2009-09-16T14:36:27.593	esData	2328	esDataEvent				
∽ 😓 esΩata	Property Archiv	ii O	1		2009-09-16T14:36:27.696	m1Pos	2329	pttDataEvent				
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QueueSize: 0					2009-09-16T14:36:28.246	esData	2334	esDataEvent				
v 🦢 pRøf					2009-09-16T14:36:28.352	m1Pos	2335	pttDataEvent				
Z Consumers: 1												
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The Suppliers: 2							Members: setpoint, re	aduock, key, urriestar				
NotifyEventChannelhactory/Stater12					setpoint / actuatorSpace	struct	Members: ptt					
NotifyEventChannelhactory/StateP4					ptt	an'ay	size: 2952					
					ptt[0]	double	0.0					
Average event rate from all subscribed channels, 9.55 events/s					ptt[1]	double	1.0					

### <u>Further details here</u>





### Logging system

- Logging is fundamental for the operation of distributed systems, in order to understand and keep track of what happens between concurrent components
   Logging is used to publish any kind of status and
- ♦ Logging is used to publish any kind of status and diagnostic information for interested clients and for archival
- The current implementation of ACS is based on the Notification Service
  - ♦ Replacement to use newer technologies may come (DDS, zeroMQ, ...)





### Logging tools: jlog logging client

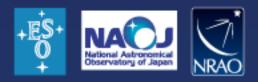
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22:04:09 🤤 Inf			
		it 'curl:///NameService' provided.	
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		Source Object	
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		Line	
		Routine	
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19:08:09.517 😟 Info	CONTROL/DV05/FrontEnd/WCA3	WCA PLL adjust to near zero	L
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19:08:09.455 😲 Info	CONTROL/DV08/FrontEnd	Optimized EDFA value 1.668773, for a target voltage of 2.5V	P
19:08:09.341 😲 Info	CONTROL/DV05/FrontEnd/WCA3	WCA Lock Acquired	Ċ
19:08:09.168 😲 Info	CONTROL/DV05/FrontEnd/WCA3	WCA Frequency set to: 9.20872e+10	T
19:08:09.149 😲 Info 19:08:08.966 😲 Info	CONTROL/PM02/FrontEnd CONTROL/DV05/FrontEnd	FrontEnd band# 3 locked at 9.208718e+10 Attempting lock with EDFA value 2.451853, and target PM current 0.000541	- Î
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- $\diamond$  Provides a unified way of dealing with errors/exceptions through the system
- ♦ CORBA supports "distributed" exceptions
- $\diamond$  The ACS Error System provides additionally the following features:
  - $\diamond$  Error format standardisation
  - $\diamond$  Error handling design patterns
  - $\diamond$  Error trace
  - ♦ Error logging
  - ♦ Synchronous and asynchronous error handling
  - $\diamond$  Error browsing and definition tools





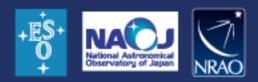
### Alarm System

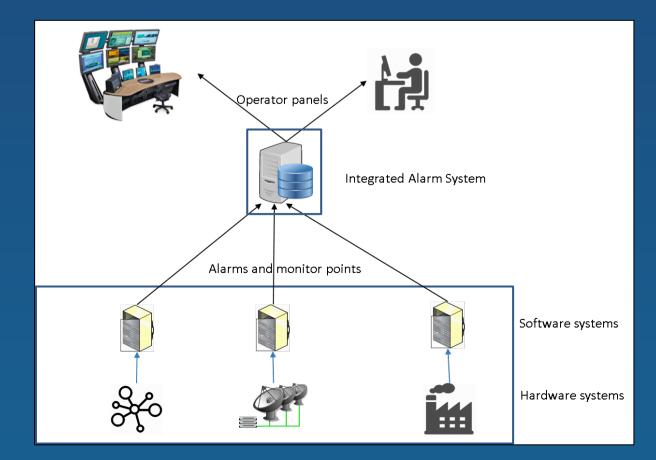
 $\diamond$  Deals with **abnormal** situations  $\diamond$  Fault states (FS)  $\diamond$  Range from severe alarms to warning states  $\diamond$  Provides  $\diamond$  FS collection, analysis and distribution, definition and archiving  $\diamond$  FS reduction  $\diamond$  Dedicated alarm consoles  $\diamond$  The ACS alarm system is a porting of the CERN LASER

system out of the box

Alma using the "Integrated Alarm" System (A. Caproni) to provide further capabilities – CTA intends to use it as well.

https://integratedalarmsystemgroup.github.io/

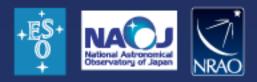






### \*Alarm System Console

Alarms																	
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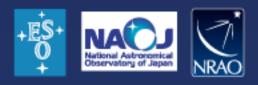




 $\diamond$  The ACS Configuration Database (CDB) addresses: defining, accessing and maintaining the configuration of a system  $\diamond$  For each component in the system, there might be a set of static (or quasi-static) configuration parameters that have to be configured in a persistent store and read when the component is started up or re-initialized.  $\diamond$  This includes the "deployment structure" of the system, i.e., which statically deployed Components are part of the system and their inter-relationships

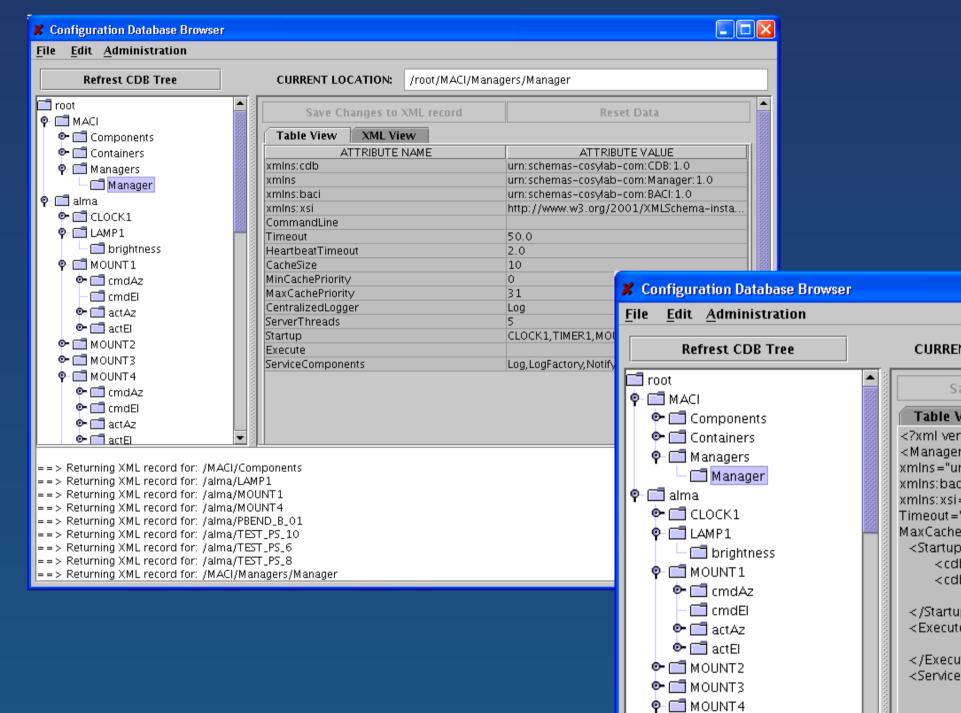
 $\diamond$  This information is used by the component/container infrastructure in runtime

 $\diamond$  See presentation of Tomás: Software deployment: Configuration Database and GIT





### Configuration Database Browser



### See here for further details: Link



RENT LOCATION:	/root/MACI/Manage	ers/Manager	
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	cosylab-com:BACI:1.		
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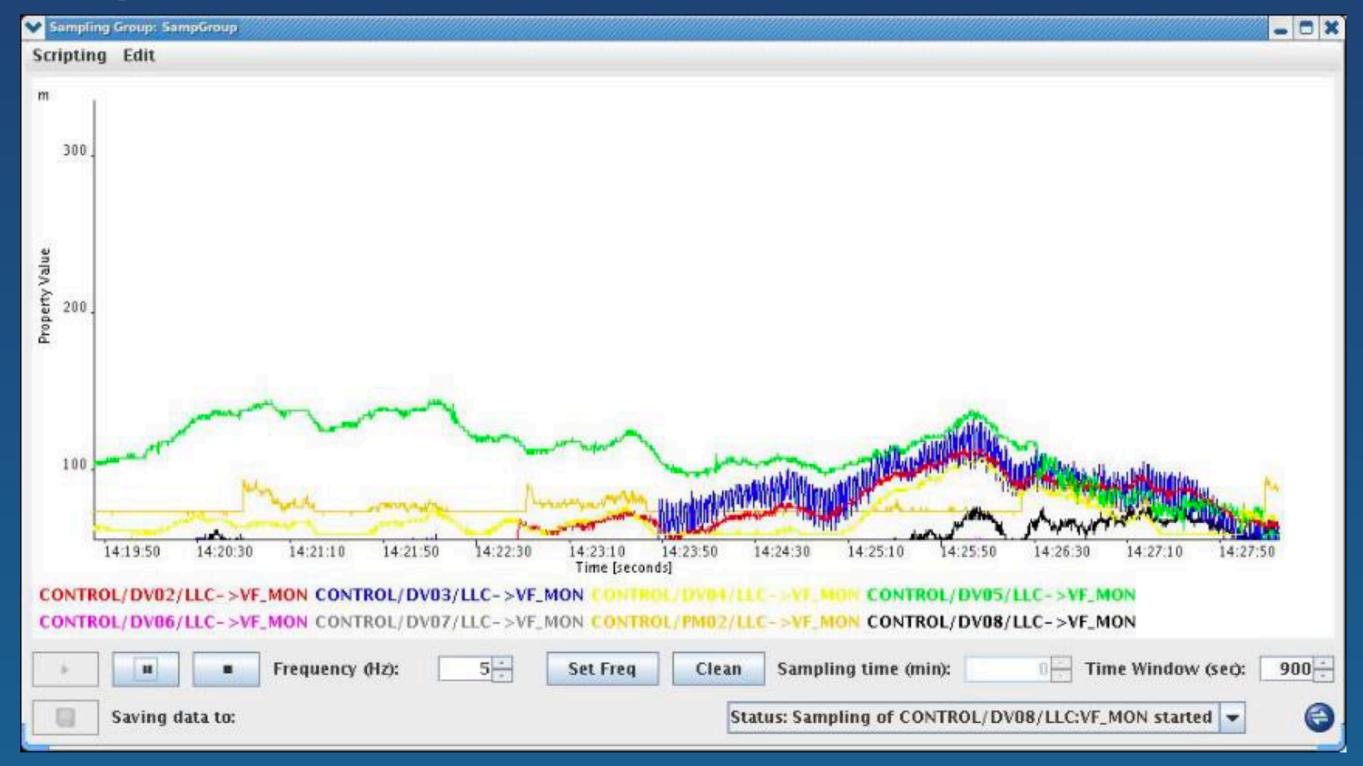
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= > Returning XML record for: /alma/PBEND\_B\_01
= > Returning XML record for: /alma/TEST\_PS\_10
= > Returning XML record for: /alma/TEST\_PS\_6
= > Returning XML record for: /alma/TEST\_PS\_8

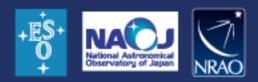


### Sampling System

Sampling of any Property
High sustained frequency
Optimized data transport
Simultaneous sampling
Plotting GUI



More details here: Link





Component simulation

♦ The component simulator is based on the CDB and Python ♦ Useful in ALMA early stages but nor much used anymore  $\diamond$  Further details: <u>Link</u>



### Questions?







National Astronomical Observatory of Japan





### Acknowledgements

ACS presentations were originally developed by the ALMA Common Software development team and has been used in many instances of training courses since 2004. Main contributors are (listed in alphabetical order): Jorge Avarias, Alessandro Caproni, Gianluca Chiozzi, Jorge Ibsen, Thomas Jürgens, Matias Mora, Joseph Schwarz, Heiko Sommer.

The Atacama Large Millimeter/submillimeter Array (ALMA), an international astronomy facility, is a partnership of Europe, North America and East Asia in cooperation with the Republic of Chile. ALMA is funded in Europe by the European Organization for Astronomical Research in the Southern Hemisphere (ESO), in North America by the U.S. National Science Foundation (NSF) in cooperation with the National Research Council of Canada (NRC) and the National Science Council of Taiwan (NSC) and in East Asia by the National Institutes of Natural Sciences (NINS) of Japan in cooperation with the Academia Sinica (AS) in Taiwan. ALMA construction and operations are led on behalf of Europe by ESO, on behalf of North America by the National Radio Astronomy Observatory (NRAO), which is managed by Associated Universities, Inc. (AUI) and on behalf of East Asia by the National Astronomical Observatory of Japan (NAOJ). The Joint ALMA Observatory (JAO) provides the unified leadership and management of the construction, commissioning and operation of ALMA.